

# Appendices

## A. Effect of a Second Shock on the Principal Hugoniot

Given an equation of state

$$P = a\mu + b\mu^2 + c(1 + \mu)E,$$

where

$$\mu = \frac{1}{V} - 1, \quad V = \text{relative volume.}$$

We wish to find how much a second compression from a point on the principal Hugoniot differs from the principal Hugoniot.

The principal Hugoniot is obtained by substituting in the equation of state the relation  $E = E_0 + 1/2(P + P_0)(V^0 - V)$  where  $E_0 = 0$ ,  $P_0 = 0$ , and  $V^0 = 1$ . For the given equation of state this yields

$$P = \frac{a\mu + b\mu^2}{1 - c\mu/2} \quad (\text{principal Hugoniot}). \quad (\text{A.1})$$

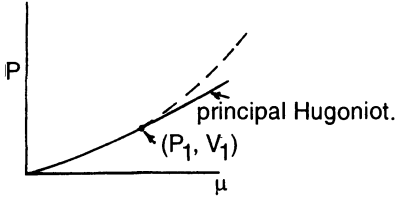
For  $\mu < 0.25$  we may write

$$P \sim a\mu + \left(b + \frac{ac}{2}\right)\mu^2 + \frac{1}{2}c\left(b + \frac{ac}{2}\right)\mu^3. \quad (\text{A.2})$$

To calculate the Hugoniot starting from the point  $(P_1, V_1, E_1)$  on the principal Hugoniot (Fig. A.1), we substitute in the equation of state the relation  $E = E_1 + 1/2(P + P_1)(V_1 - V)$ . Let  $V_1 = 1 - \delta$ , then  $E_1 = 1/2P_1\delta$ .

We have

$$\begin{aligned} P &= a\mu + b\mu^2 + c(1 + \mu) \left[ E + \frac{P + P_1}{2}(V_1 - V) \right] \\ &= a\mu + b\mu^2 + \frac{c}{2} \left[ P_1 \frac{\delta}{V} + P \left( \mu - \frac{\delta}{V} \right) + P_1 \left( \mu - \frac{\delta}{V} \right) \right] \\ &= a\mu + b\mu^2 + \frac{c}{2} \left[ P \left( \mu - \frac{\delta}{V} \right) + P_1\mu \right]. \end{aligned}$$



**Fig. A.1.** Hugoniot from point  $(P_1, V_1)$  on principal Hugoniot

The Hugoniot for points above the initial point  $(P_1, V_1 = 1 - \delta, E_1 = \frac{P_1 \delta}{2})$  is

$$P = \frac{a\mu + b\mu^2 + \frac{c}{2}P_1\mu}{1 - \frac{c}{2}\left(\mu - \frac{\delta}{V}\right)}. \tag{A.3}$$

Expanding, we get

$$\begin{aligned} P &= a\mu + b\mu^2 + \frac{c}{2}P_1\mu + \frac{ac}{2}\mu\left(\mu - \frac{\delta}{V}\right) \\ &\quad + \frac{bc}{2}\mu^2\left(\mu - \frac{\delta}{V}\right) + \frac{c^2}{4}P_1\mu\left(\mu - \frac{\delta}{V}\right) + \frac{c^2}{4}a\mu\left(\mu - \frac{\delta}{V}\right)^2 \\ &= a\mu + \left(b + \frac{ac}{2}\right)\mu^2 + \frac{c}{2}\left(b + \frac{ac}{2}\right)\mu^3 - \frac{ac}{2}\mu\frac{\delta}{V} \\ &\quad - \frac{bc}{2}\mu^2\frac{\delta}{V} - \frac{c^2}{2}a\mu^2\frac{\delta}{V} + \frac{c^2}{4}a\mu\frac{\delta^2}{V^2} \\ &\quad + \frac{c}{2}\mu P_1\left[1 + \frac{c}{2}\left(\mu - \frac{\delta}{V}\right)\right]. \end{aligned}$$

Rearranging the terms and replacing  $P_1$  by (A.2) we obtain

$$\begin{aligned} P &= \frac{a\mu + \left(b + \frac{ac}{2}\right)\mu^2 + \frac{c}{2}\left(b + \frac{ac}{2}\right)\mu^3}{\underline{1 - \frac{c}{2}\left[a\frac{\delta}{V} + \left(b + \frac{ac}{2}\right)\mu\frac{\delta}{V} - \frac{c}{2}a\frac{\delta^2}{V^2}\right]}} \\ &\quad + \frac{c}{2}\mu\left[\underline{a\mu_1 + \left(b + \frac{ac}{2}\right)\mu_1^2 + \frac{1}{2}c\left(b + \frac{ac}{2}\right)\mu_1^3 + \dots}\right]. \end{aligned} \tag{A.4}$$

The underlined terms in (A.4) are the same as the principal Hugoniot. Since  $\frac{\delta}{V} \sim \mu_1$  and  $c$  is usually between 1 and 2, equation (A.4) is very nearly equal to the principal Hugoniot except for high order terms.

## B. Finite Difference Program for One Space Dimension and Time

The partial differential equations and the corresponding finite difference equations are those used by the KO computer program. Time-dependent flows in one space variable,  $r$ , are described for plane ( $d = 1$ ), cylindrical ( $d = 2$ ), and spherical ( $d = 3$ ) geometries.

### B.1 Fundamental Equations

Equation of motion

$$\frac{\rho_0 \dot{U}}{V} = \frac{\partial \Sigma_r}{\partial r} + (d-1) \frac{\Sigma_r - \Sigma_\theta}{r},$$

where  $U$  is the particle velocity.

Conservation of mass

$$\frac{dM}{dt} = 0$$

with  $M$  a mass element.

3. First law of thermodynamics

$$\dot{E} - V[s_1 \dot{\epsilon}_1 + (d-1)s_2 \dot{\epsilon}_2] + (P+q)\dot{V} = 0.$$

4. Velocity strains

$$\dot{\epsilon}_1 = \frac{\partial U}{\partial r},$$

$$\dot{\epsilon}_2 = \frac{U}{r}.$$

5. Stress deviators

$$\dot{s}_1 = 2\mu \left( \dot{\epsilon}_1 - \frac{1}{3} \frac{\dot{V}}{V} \right),$$

$$\dot{s}_2 = 2\mu \left( \dot{\epsilon}_2 - \frac{1}{3} \frac{\dot{V}}{V} \right),$$

$$\dot{s}_3 = 2\mu \left( \dot{\epsilon}_3 - \frac{1}{3} \frac{\dot{V}}{V} \right).$$

Note: Three stresses are identified here, even though they are not all required in order to maintain an analogy with the two and three dimensional programs.

6. Pressure equation of state

$$P = a(\eta - 1) + b(\eta - 1)^2 + c(\eta - 1)^3 + d\eta E$$

with  $\eta = 1/V = \rho/\rho_0$  and where  $a$ ,  $b$ ,  $c$ , and  $d$  are equation-of-state constants.

## 7. Total stresses

$$\begin{aligned}\Sigma_r &= -(P + q) + s_1 \\ \Sigma_\theta &= -(P + q) + s_2.\end{aligned}$$

## 8. Artificial viscosity

$$q = C_0^2 \frac{\rho_0}{V} \left( \frac{\partial U}{\partial r} \right)^2 (\Delta r)^2 + C_L \frac{\rho_0 a}{V} \left( \frac{\partial U}{\partial r} \right) \Delta r,$$

where  $C_L$  and  $C_0$  are constants,  $a = \sqrt{P/\rho}$ , and  $\Delta r$  is the grid spacing.

## 9. Von Mises yield condition

$$(s_1^2 + s_2^2 + s_3^2) - \frac{2}{3}(Y^0)^2 \leq 0$$

with  $Y^0$  the plastic flow stress.

## B.2 Finite Difference Equations

## 1. Mass zoning

$$m_{j+\frac{1}{2}} = \frac{\rho_0}{V_0} \left[ \frac{(r_{j+1}^0)^d - (r_j^0)^d}{d} \right] \quad \left\{ \begin{array}{ll} \text{plane:} & d = 1 \\ \text{cylindrical:} & d = 2 \\ \text{spherical:} & d = 3 \end{array} \right.$$

where  $\rho_0$  is the equation-of-state reference density and  $V_0$  the initial relative volume.

## 2. Equation of motion

$$U_j^{n+\frac{1}{2}} = U_j^{n-\frac{1}{2}} + \frac{\Delta t^n}{\phi_j^n} \left[ (\Sigma_r)_j^{n+\frac{1}{2}} - (\Sigma_r)_j^{n-\frac{1}{2}} \right] + \Delta t^n (\beta_j^n)(d-1),$$

where

$$\begin{aligned}(\Sigma_r)_j^{n+\frac{1}{2}} &= \left[ -(P^n + q^{n-\frac{1}{2}}) + s_1^n \right]_{j+\frac{1}{2}}, \\ (\Sigma_\theta)_j^{n+\frac{1}{2}} &= \left[ -(P^n + q^{n-\frac{1}{2}}) + s_2^n \right]_{j+\frac{1}{2}}, \\ \phi_j^n &= \frac{1}{2} \left[ \rho_{0,j+\frac{1}{2}} \left( \frac{r_{j+1}^n - r_j^n}{V_{j+\frac{1}{2}}^n} \right) + \rho_{0,j-\frac{1}{2}} \left( \frac{r_j^n - r_{j-1}^n}{V_{j-\frac{1}{2}}^n} \right) \right], \\ \beta_j^n &= \frac{1}{2} \left\{ \left[ \frac{(\Sigma_r)_j^{n+\frac{1}{2}} - (\Sigma_\theta)_j^{n+\frac{1}{2}}}{\frac{1}{2}(r_{j+1}^n + r_j^n)} \right] \left( \frac{V^n}{\rho_0} \right)_{j+\frac{1}{2}} \right. \\ &\quad \left. + \left[ \frac{(\Sigma_r)_j^{n-\frac{1}{2}} - (\Sigma_\theta)_j^{n-\frac{1}{2}}}{\frac{1}{2}(r_j^n + r_{j-1}^n)} \right] \left( \frac{V^n}{\rho_0} \right)_{j-\frac{1}{2}} \right\}.\end{aligned}$$

3. Conservation of mass

$$V_{j+\frac{1}{2}}^{n+1} = \frac{\rho_0}{m_{j+\frac{1}{2}}} \left[ \frac{(r_{j+1})^d - (r_j)^d}{d} \right]^{n+1},$$

$$r_j^{n+1} = r_j^n + U_j^{n+\frac{1}{2}} \Delta t^{n+\frac{1}{2}}.$$

4. Calculation of velocity strains

$$(\dot{\epsilon}_1)_{j+\frac{1}{2}}^{n+\frac{1}{2}} = \frac{U_{j+1}^{n+\frac{1}{2}} - U_j^{n+\frac{1}{2}}}{r_{j+1}^{n+\frac{1}{2}} - r_j^{n+\frac{1}{2}}},$$

$$(\dot{\epsilon}_2)_{j+\frac{1}{2}}^{n+\frac{1}{2}} = \frac{U_{j+1}^{n+\frac{1}{2}} + U_j^{n+\frac{1}{2}}}{r_{j+1}^{n+\frac{1}{2}} + r_j^{n+\frac{1}{2}}},$$

$\dot{\epsilon}_2 = 0$  for  $d = 1$ .

5. Calculation of stresses

(a) Stress deviators

$$\left( \begin{array}{l} (s_1)_{j+\frac{1}{2}}^{n+1} = (s_1)_{j+\frac{1}{2}}^n + 2\mu \left[ (\dot{\epsilon}_1)_{j+\frac{1}{2}}^{n+\frac{1}{2}} \Delta t^{n+\frac{1}{2}} - \frac{1}{3} \left( \frac{V^{n+1} - V^n}{V^{n+\frac{1}{2}}} \right)_{j+\frac{1}{2}} \right] \\ (s_2)_{j+\frac{1}{2}}^{n+1} = (s_2)_{j+\frac{1}{2}}^n + 2\mu \left[ (\dot{\epsilon}_2)_{j+\frac{1}{2}}^{n+\frac{1}{2}} \Delta t^{n+\frac{1}{2}} - \frac{1}{3} \left( \frac{V^{n+1} - V^n}{V^{n+\frac{1}{2}}} \right)_{j+\frac{1}{2}} \right] \\ (s_3)_{j+\frac{1}{2}}^{n+1} = - \left[ (s_1)_{j+\frac{1}{2}}^{n+1} + (s_2)_{j+\frac{1}{2}}^{n+1} \right]. \end{array} \right.$$

(b) Pressure equation of state

$$P_{j+\frac{1}{2}}^{n+1} = A(\eta_{j+\frac{1}{2}}^{n+1}) + B(\eta_{j+\frac{1}{2}}^{n+1})E_{j+\frac{1}{2}}^{n+1}.$$

6. Von Mises yield condition

$$(s_1^2 + s_2^2 + s_3^2)^{n+1} - \frac{2}{3}(Y^0)^2 = K^{n+1}.$$

If  $K^{n+1} \leq 0$  the material is within the elastic limit. If  $K^{n+1} > 0$  multiply the stress deviators by  $\sqrt{2/3}Y^0/\sqrt{s_1^2 + s_2^2 + s_3^2}$ .

7. Artificial viscosity

$$q_{j+\frac{1}{2}}^{n+\frac{1}{2}} = C_0^2 \rho_{j+\frac{1}{2}}^{n+\frac{1}{2}} (U_{j+1}^{n+\frac{1}{2}} - U_j^{n+\frac{1}{2}})^2 + C_L a \rho_{j+\frac{1}{2}}^{n+\frac{1}{2}} |U_{j+1}^{n+\frac{1}{2}} - U_j^{n+\frac{1}{2}}|.$$

Calculate only if  $U_{j+1}^{n+\frac{1}{2}} < U_j^{n+\frac{1}{2}}$  and  $(V_{j+\frac{1}{2}}^{n+1} - V_{j+\frac{1}{2}}^n) < 0$ . Here  $a = \sqrt{P/\rho}$ , where  $P$  is the local pressure and  $C_0 = 2$ ;  $C_L = 1$ .

8. Energy equations

The change in the internal energy,  $\Delta E$ , is composed of a hydrodynamic component and a distortion component:

$$\Delta E = -(P + q)\Delta V + \Delta Z.$$

The change in distortion energy,  $\Delta Z$ , is

$$(\Delta Z)_{j+\frac{1}{2}}^{n+\frac{1}{2}} = V_{j+\frac{1}{2}}^{n+\frac{1}{2}} [s_1 \dot{\epsilon}_1 + (d-1)s_2 \dot{\epsilon}_2]_{j+\frac{1}{2}}^{n+\frac{1}{2}} \Delta t^{n+\frac{1}{2}},$$

where

$$s_1^{n+\frac{1}{2}} = \frac{1}{2}(s_1^{n+1} + s_1^n) \text{ etc.}$$

The total internal energy,  $E$ , is

$$(E)_{j+\frac{1}{2}}^{n+1} = \left( \frac{E^n - \left\{ \frac{1}{2}[A(\eta^{n+1}) + \underline{P}^n] + \bar{q} \right\} [V^{n+1} - V^n] + \Delta}{1 + \frac{1}{2}[B(\eta^{n+1})][V^{n+1} - V^n]} \right)$$

where

$$\bar{q} = \frac{1}{2}(q^{n+\frac{1}{2}} + q^{n-\frac{1}{2}}).$$

This equation assumes that the equation of state has the form

$$P = A(\eta) + B(\eta)E.$$

9. Time steps

$$\Delta t^{n+\frac{3}{2}} = \frac{2}{3} \frac{\Delta r^{n+1}}{\sqrt{a^2 + b^2}} \Big|_{\min \text{ over } j},$$

$$\Delta r^{n+1} = r_{j+1}^{n+1} - r_j^{n+1}$$

where  $a$  is the local sound speed and

$$b = 8(C_0^2 + C_L)\Delta r^{n+1} \left( \frac{\dot{V}}{V} \right)^{n+\frac{1}{2}};$$

$$b = 0 \text{ if } \frac{\dot{V}}{V} \geq 0.$$

If  $\Delta t^{n+\frac{3}{2}} > (1.1)\Delta t^{n+\frac{1}{2}}$ , use  $\Delta t^{n+\frac{3}{2}} = (1.1)\Delta t^{n+\frac{1}{2}}$

$$\Delta t^{n+1} = \frac{1}{2}(\Delta t^{n+\frac{3}{2}} + \Delta t^{n+\frac{1}{2}}).$$

B.3 Boundary Conditions

At an outside regional boundary  $J$  (Fig. B.1)

$$\phi_J^n = \frac{1}{2}\rho_{0,J-\frac{1}{2}} \left( \frac{r_J^n - r_{J-1}^n}{V_{J-\frac{1}{2}}^n} \right)$$

$$\beta_J^n = \left[ \frac{(\Sigma_r)_{J-\frac{1}{2}}^n - (\Sigma_\theta)_{J-\frac{1}{2}}^n}{\frac{1}{2}(r_J^n + r_{J-1}^n)} \right] \left( \frac{V_n}{\rho_0} \right)_{J-\frac{1}{2}}.$$

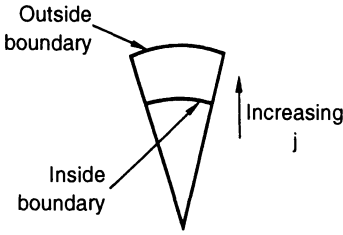


Fig. B.1. Grid boundary scheme

At an inside regional boundary  $J$

$$\phi_j^n = \frac{1}{2} \rho_{0j+\frac{1}{2}} \left( \frac{r_{j+1}^n - r_j^n}{V_{j+\frac{1}{2}}^n} \right)$$

$$\beta_j^n = \left[ \frac{(\Sigma_r)_{j+\frac{1}{2}}^n - (\Sigma_\theta)_{j+\frac{1}{2}}^n}{\frac{1}{2}(r_j^n + r_{j+1}^n)} \right] \left( \frac{V^n}{\rho_0} \right)_{j+\frac{1}{2}}$$

For a free surface at  $j = J$ , the stresses are set to zero at  $J + \frac{1}{2}$  for an outside free surface or at  $J - \frac{1}{2}$  for an inside free surface.

### B.4 Opening and Closing Voids

Many calculations require a routine that will permit a material to break or spall. An additional requirement is a routine that will allow two materials originally separated to join during the course of a calculation. Details of these routines are given below.

(a) Opening of a void

Let

$$P_j^n = \frac{1}{2} (P_{j+\frac{1}{2}}^n + P_{j-\frac{1}{2}}^n)$$

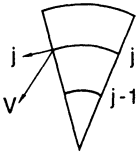
$$V_j^n = \frac{1}{2} (V_{j+\frac{1}{2}}^n + V_{j-\frac{1}{2}}^n).$$

If  $P_j^{n+1} < P_S$  and  $V_j^{n+1} > V_S$  where  $P_S, V_S$  are material constants, then introduce a new interface at  $j$  with the label  $V$  (Fig. B.2), with

$$r_V^{n+1} = r_j^{n+1}$$

$$U_V^{n+\frac{1}{2}} = U_j^{n+\frac{1}{2}}.$$

In subsequent time steps, both  $j$  and  $V$  are treated as free surfaces where  $V$  is an outside boundary and  $j$  an inside boundary (refer to Sect. B.3). The criteria for the opening of a void given above are meant to serve as an example. In general, the criteria for the calculation of spall involve other parameters, stress gradients for example.



**Fig. B.2.** Scheme for void opening

(b) Closing of a void

At the beginning of each time step, the new positions of  $r_V$  and  $r_j$  are calculated first, using a  $\Delta t$  that is 20% larger than the normal  $\Delta t$  for this time step. If  $r_V^{n+1} < r_j^{n+1}$ , calculate all grid points with the normal  $\Delta t$ . If  $r_V^{n+1} \geq r_j^{n+1}$ , solve for a new  $\Delta t$  as follows:

$$\begin{aligned}
 W &= U_j^{n-\frac{1}{2}} - U_V^{n-\frac{1}{2}}, \\
 R &= r_j^n - r_V^n, \\
 A &= \left[ \frac{(\Sigma_r^n)_{j+\frac{1}{2}}}{\phi_j^n} + \frac{(\Sigma_r^n)_{j-\frac{1}{2}}}{\phi_V^n} + (\beta_V^n + \beta_j^n)(d-1) \right], \\
 B &= 2W + A\Delta t^{n-\frac{1}{2}}.
 \end{aligned}$$

Note: In the calculation of  $\phi$  and  $\beta$ , the subscript  $V$  refers to an outside regional boundary and the subscript  $j$  to an inside regional boundary, see Sect. B.3. Then

$$A(\Delta t^{n+\frac{1}{2}})^2 + B\Delta t^{n+\frac{1}{2}} + 2R = 0.$$

To solve for  $\Delta t^{n+\frac{1}{2}}$ :

$$\Delta t_i - \Delta t_{i+1} = \frac{A(\Delta t_i)^2 + B\Delta t_i + 2R}{2A\Delta t_i + B}.$$

Start with  $\Delta t_i = 0$  and iterate until  $(\Delta t_i - \Delta t_{i+1}) = 0$ . Solve equations of motion for one time step with:

$$\begin{aligned}
 \Delta t^{n+\frac{1}{2}} &= \Delta t_{i+1} \\
 \Delta t^n &= \frac{1}{2}(\Delta t_{i+1} + \Delta t^{n-\frac{1}{2}}).
 \end{aligned}$$

Remove the free surface boundary condition on  $j$  and set

$$\begin{aligned}
 r_V^{n+1} &= r_j^{n+1} \\
 U_j^{n+\frac{1}{2}} &= \frac{m_{j+\frac{1}{2}} *U_j^{n+\frac{1}{2}} + m_{j-\frac{1}{2}} U_V^{n+\frac{1}{2}}}{m_{j+\frac{1}{2}} + m_{j-\frac{1}{2}}},
 \end{aligned}$$

where  $*U_j^{n+\frac{1}{2}}$  is the velocity of interface  $j$  when the void closed.

Note: no attempt has been made to conserve energy after setting the velocity  $U_j$  to the value required to conserve momentum.